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BUILDING TOOLKIT FOR MULTI-AGENT SYSTEMS

WHAT IS A MULTI-AGENT SYSTEM?

- ▶ A multi-agent system (MAS or "self-organized system") is a computerized system composed of multiple interacting intelligent agents. Multi-agent systems can solve problems that are difficult or impossible for an individual agent or a monolithic system to solve.

THE PROBLEM?

An aerial, high-angle photograph of a massive, curved concrete structure, possibly a bridge or a large-scale architectural element. The structure is composed of many parallel concrete slabs, creating a textured, ribbed appearance. A single person is walking along the top edge of the curve, providing a sense of scale. The lighting is dramatic, with strong shadows and highlights, suggesting a low sun position. The overall color palette is dark and monochromatic, with the concrete appearing in shades of grey and black.

GENERALIZED MULTI-AGENT
EVALUATION PLATFORM

ARENA

ARENA

- ▶ Unity based
- ▶ Compatible with different types of games
- ▶ Provides an standard for testing multi agent games
- ▶ Reinforcement learning games
- ▶ 35 games, 27 have never been investigated, 8 already existed and were improved.
- ▶ 5 different types of agents

WHAT ARENA IS HOPING TO IMPROVE/CONTRIBUTE

- ▶ Boosting creativity through multi-agent communication
- ▶ Agents that can be used in different games
- ▶ Different training schemes
- ▶ Configurable social relations (by different reward settings)
- ▶ Creating new games and AI solutions to yet unsolved game problems

ARENA VS OTHER SYSTEMS

- ▶ DeepLearning
- ▶ PhychLab
- ▶ Malmo

OUR EXPERIENCE

TESTING ARENA

INSTALLATION

- ▶ Simple
- ▶ Well documented
- ▶ Only requires unity and git

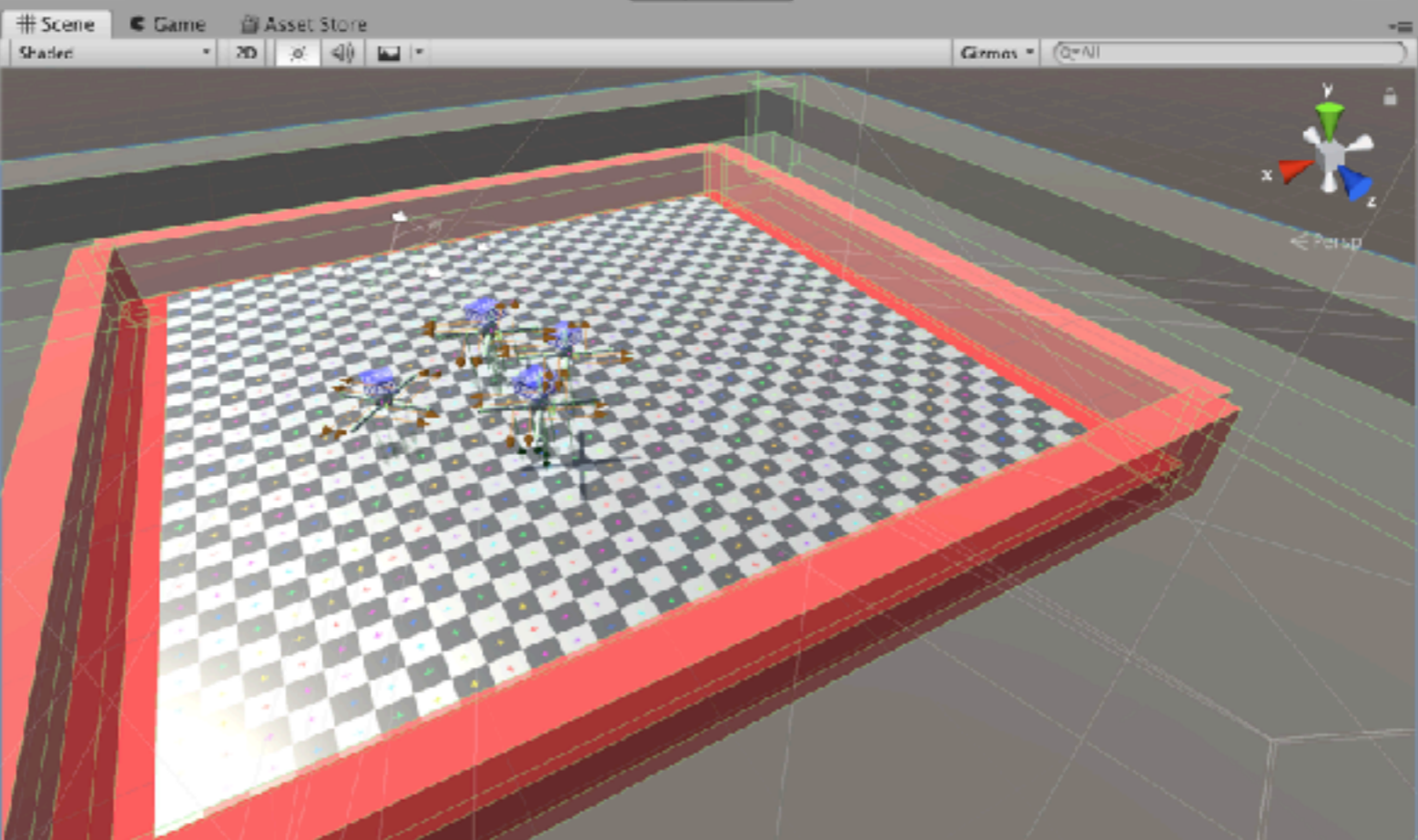
INTERFACE

- ▶ Friendly
- ▶ Intuitive
- ▶ Well explained



Hierarchy

- Prueba1a*
 - Main Camera
 - GlobalManager
 - TopDownCamera
 - VisualizationCamera
 - World
 - Team1
 - ArenaCrawlerAgent-v1 (2)
 - ArenaCrawlerAgent-v1 (3)
 - Team2
 - ArenaCrawlerAgent-v1
 - ArenaCrawlerAgent-v1 (1)
 - Directional Light



Inspector

GlobalManager Static

Tag: Unassigned Layer: Default

Prefab: Open Select Overrides

Transform

Position X: 9.8789 Y: 10.130 Z: 1.8498

Rotation X: 0 Y: 0 Z: 0

Scale X: 1 Y: 1 Z: 1

Arena Node (Script)

Script: ArenaNode

Node Settings

Node ID: 0

Living Condition

Max Num Living Steps: 1000

Living Condition: At Least Specific Number 1

At Least Specific Num1: 2

At Least Specific Portic: 0.5

Reward Scheme

Reward Scheme Scale: 100

Reward Functions (Competitive)

Is Reward Ranking:

Ranking Win Type: Depart

Is Penalize Tie:

Reward Functions (Collaborative)

Is Reward Distance:

Distance Base 1: None (Game Object)

Distance Base 2: None (Game Object)

Is Reward Time:

Time Win Type: Leader

Utils

Transform Reinitializers

Global Manager (Script)

Script: GlobalManager

Broadcast Hub

Add New Remove Last

Brains: Control

GeneralPlayerDiscrete

Max Steps: 0

Project Console

Create

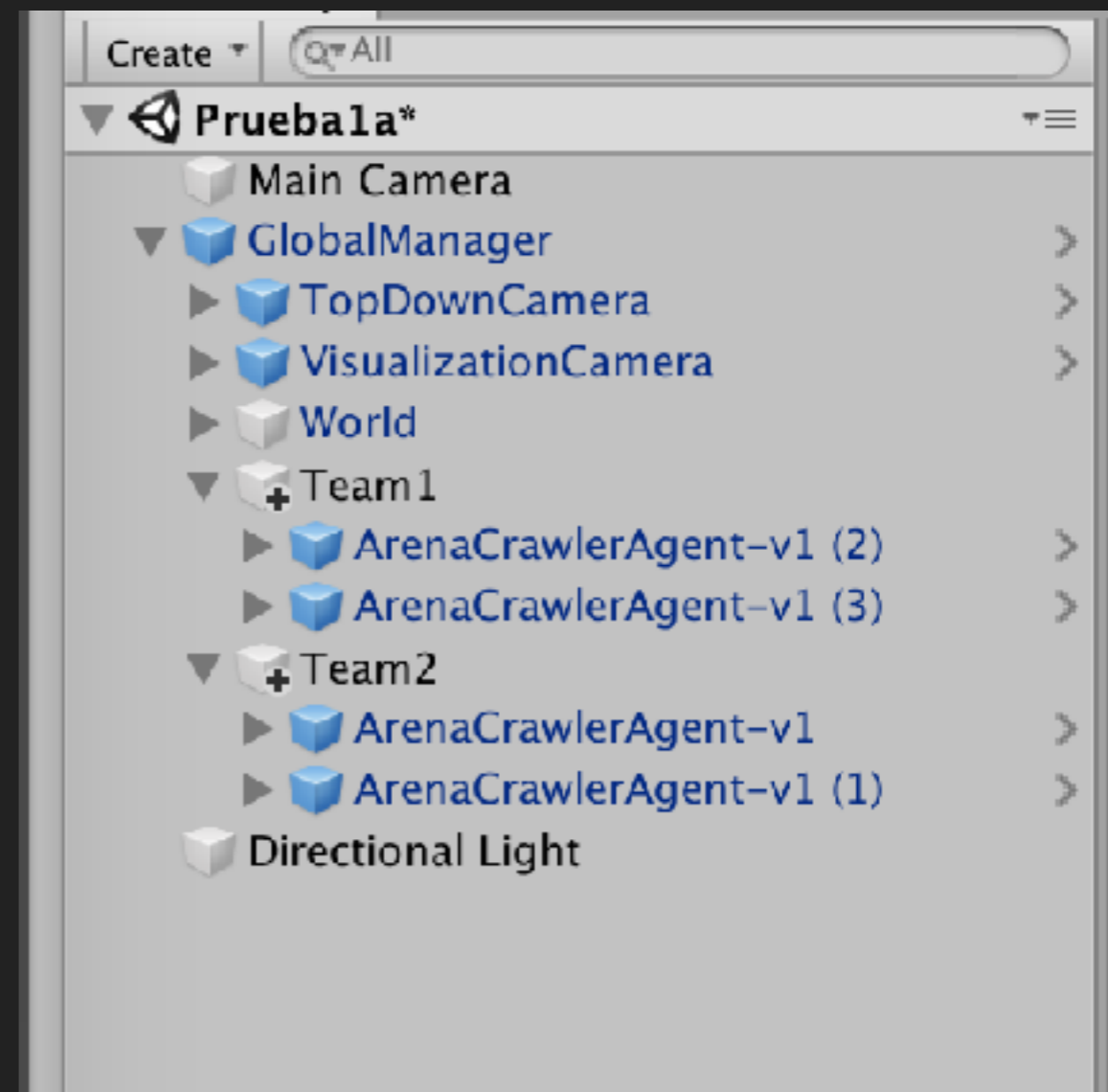
- Destroyable
- Disturber
- Eatable
- Effect
- Goal
- KillGate
- Playground
- UI
- SharedScripts
- ThirdPartyAssets
 - BarcadeGamesAssetPack
 - Boxing
 - CardGameObjects
 - EasyRoads3DAssets
 - FantasyDefensiveStructures
 - FenceChained
 - FloodedGrounds
 - FreeTrees

Assets > AranaSDK > AgentPrefabs > BasicAgent

BasicAgent1 BasicAgentLV1 BasicAgentLV2 BasicPlayer BasicPlayerN... Example Gunner-BES...

SOCIAL TREE CONFIGURATION

- ▶ Each Arena node has an ID
- ▶ Global manager that works as a root
- ▶ Each node control the others on the bottom
- ▶ Configurable settings like collaborative and comparative modality



REWARD SCHEMES

Reward Scheme

Reward Scheme Scale

Reward Functions (Competitive)

Is Reward Ranking

Ranking Win Type

Is Penalize Tie

Reward Functions (Collaborative)

Is Reward Distance

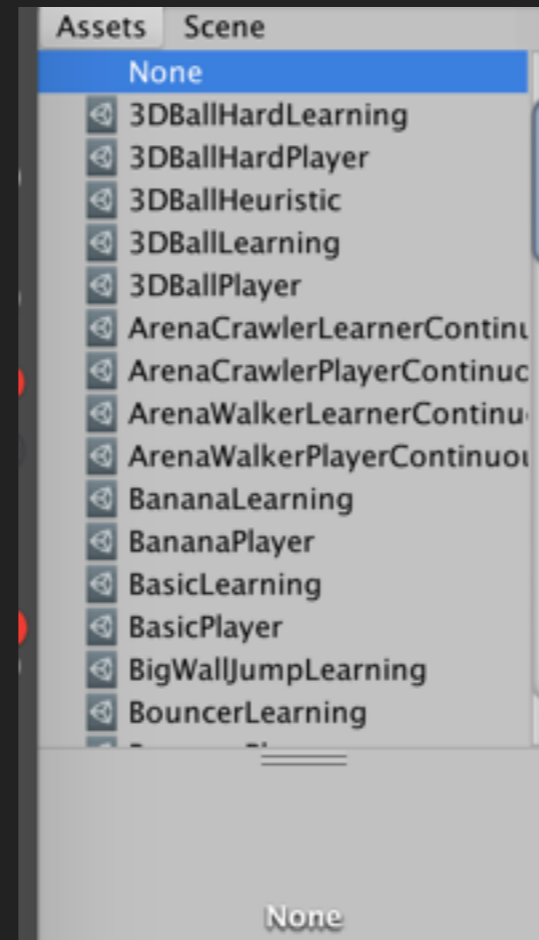
Distance Base 1

Distance Base 2

Is Reward Time

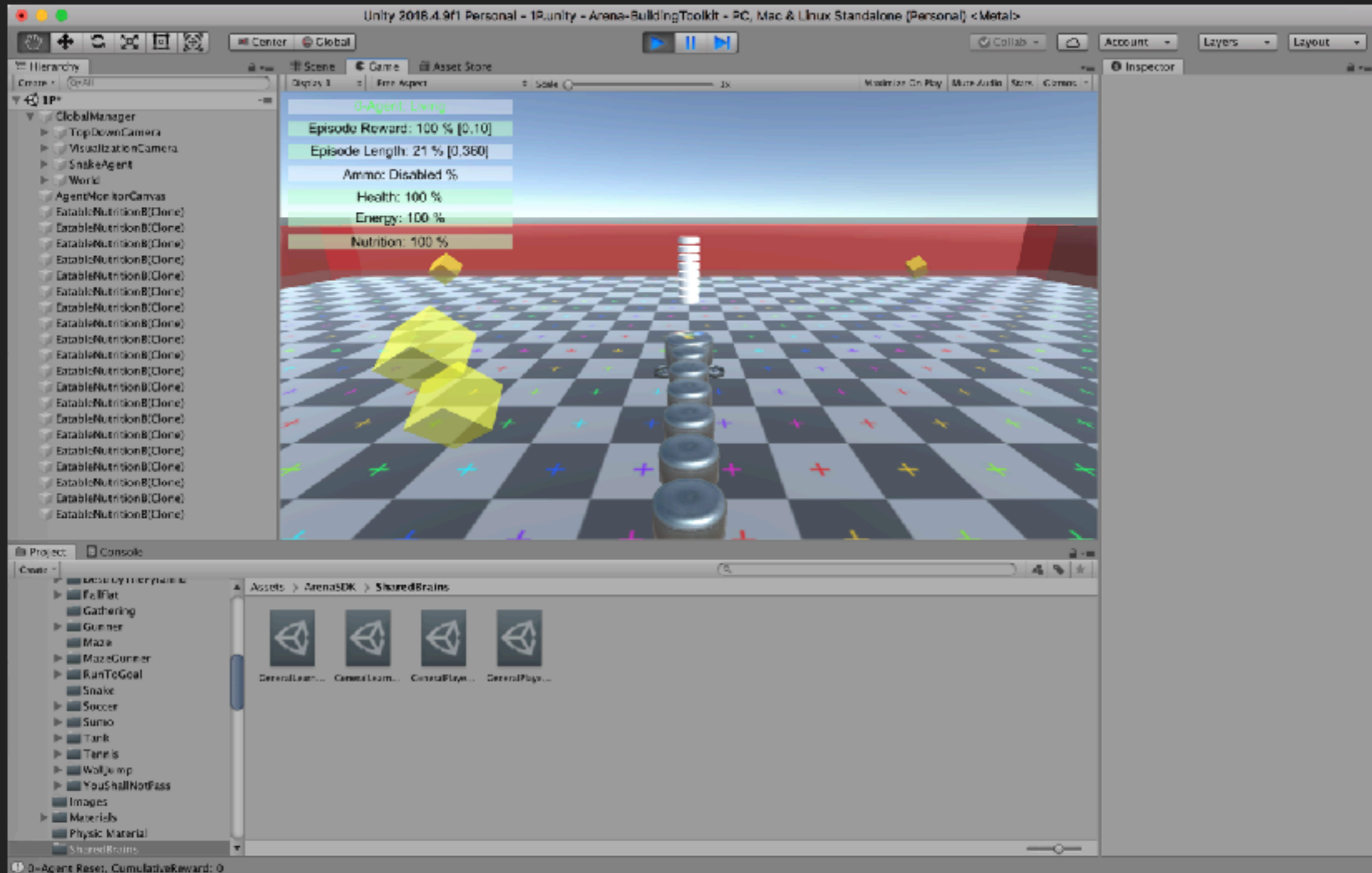
Time Win Type

BRAINS

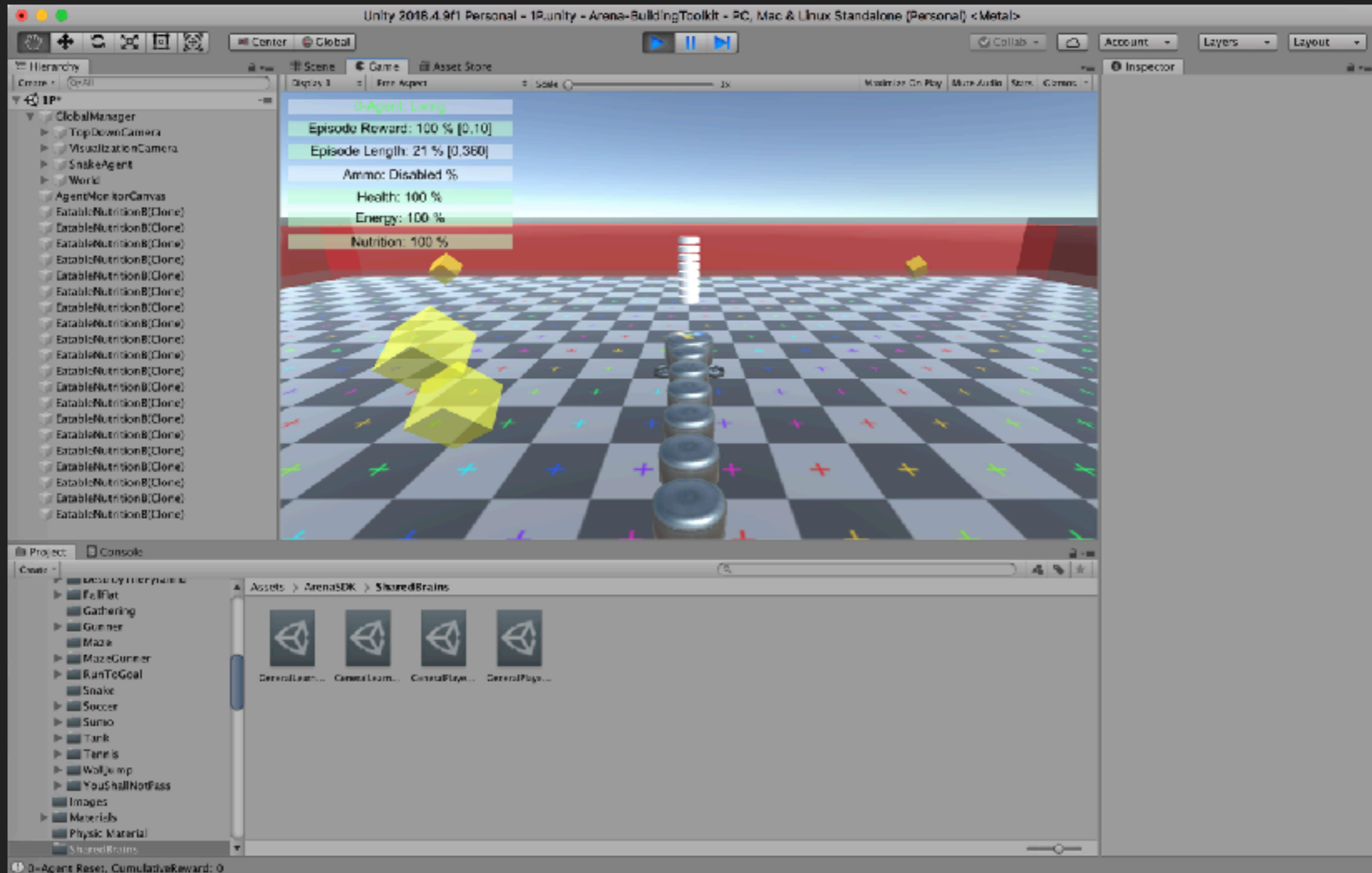


USING IT?

SIMPLE GAME (NO BRAIN)



SIMPLE GAME (BRAIN)



CONCLUSIONS

- ▶ Very good software
- ▶ Designed for researchers with advanced knowledge about python, reinforcement learning and Unity
- ▶ It achieves its intended goal
- ▶ There should be more documentation
- ▶ We'd like a version in which learning models can be set easily for people like us.